

MagneTruck™: A New Concept for Zero-Emission Goods Movement

Presentation to Port of Los Angeles
18 March 2009



Agenda

- General Atomics Overview
 - Company History
 - Relevant Programs and Technologies
- Concepts for Port-Related Transportation
 - Overview
 - ECCO™ Maglev Systems
 - LIM-Rail™ Systems
 - Road Systems
- Business Considerations
 - Risk and Return
 - Strategy
 - Open Discussion of Port Needs and Potential Opportunities



GENERAL ATOMICS OVERVIEW

Key General Atomics Business Areas

Founded: 1955
Ownership: Privately Held
Employees: Over 5,000 Worldwide



Defense

- UAV Systems
- Advanced Sensors
- Naval Ship Electrification
- Weapons Destruction
- EMALS/AAG
- Rail-Guns



Energy

- Fusion
- Fission Reactors (HTGR)
- Uranium Mining
- Algae Synfuels



Transportation

- Linear Motor Transportation Technologies
- Maglev Systems
- Streetcar Refurbishment
- Mining Truck Drives



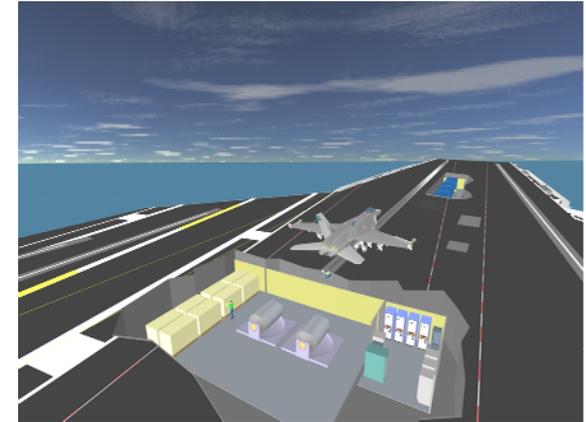
Electric Transportation Technologies Use Core GA Competencies



Inverters for 400-ton mining trucks, light and heavy rail

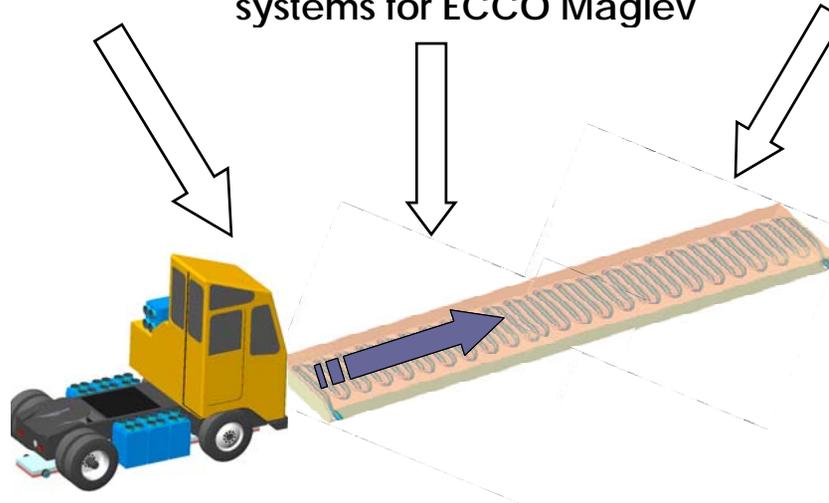


Linear electric propulsion, control, and train protection systems for ECCO Maglev



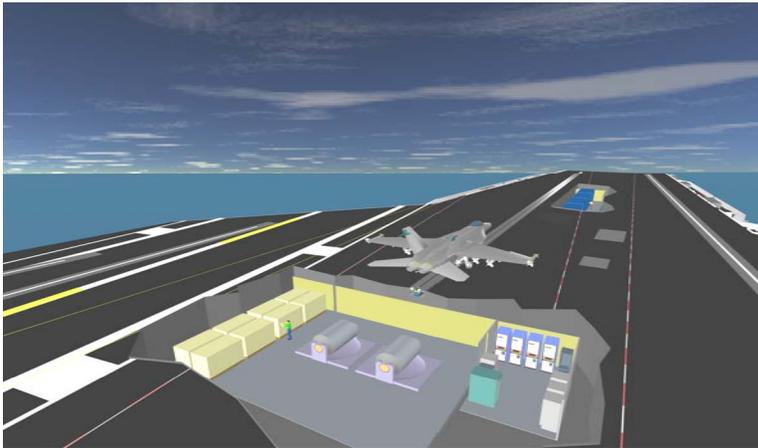
Launch systems with 50-year design life in full-scale development

All electric truck uses existing chassis replacing the diesel engine with an all-electric drive-train and onboard energy storage system (*patent pending*).



Linear motor imbedded below road surface propels the vehicle and charges the energy storage system while vehicle is automatically transported to its destination (*patent pending*).

ElectroMagnetic Aircraft Launch (EMALS) and Recovery (AAG) Systems



GA EMALS Land-Based Testing Using Full-Scale 150 ft. Long Launch Motor in Lakehurst, N.J.



9,800 lbs. @ 150 knots (173 mph)



GA Maglev Projects



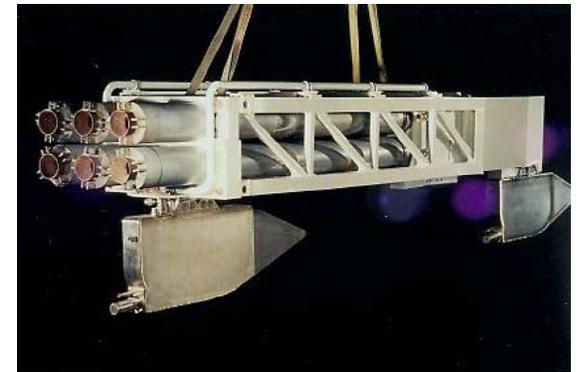
FTA Urban Maglev



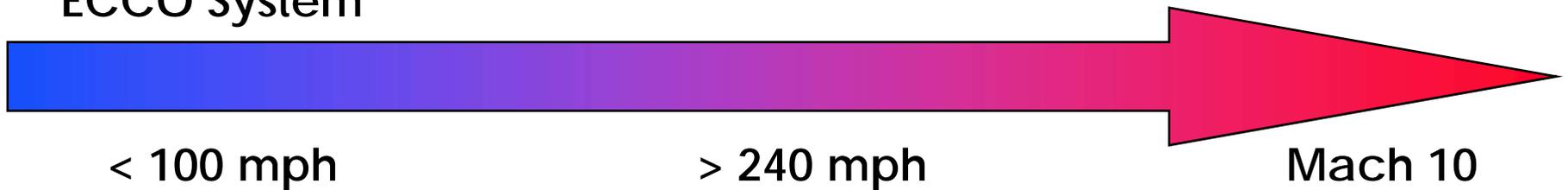
ECCO System



California-Nevada
Maglev



Air Force
Holloman



< 100 mph

> 240 mph

Mach 10

CONCEPTS FOR PORT-RELATED TRANSPORTATION

- Overview
- ECCO Maglev Systems
- LIM-Rail™ Systems
- Road Systems

Evolution from Maglev to MagneTruck™

2000	2001	2002	2003	2004	2005	2006	2007	2008	2009
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Urban Maglev Program

- Funded by FTA and Penn DOT, with GA cost share
- Licensed Livermore “Halbach Array” maglev technology
- 400-foot test track demonstrates proof-of-concept in 2004
- Developed levitation, propulsion, guidance, control, and ATP



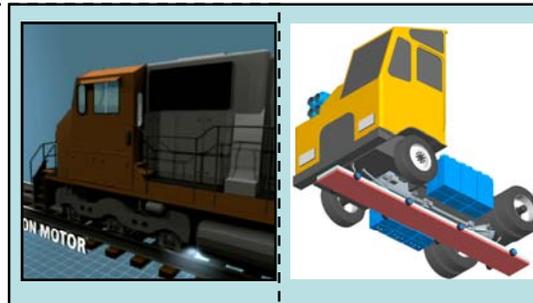
Electromagnetic Cargo Conveyor (ECCO)

- ECCO concept using maglev for goods movement originated by CSULB
- Developed for port applications using same GA passive maglev (“Halbach Array”) technology as Urban Maglev Program



Existing Infrastructure Solutions

- Concepts using existing rail (e.g., LIM-Rail)
- Concepts that can operate at port terminals
- Concepts that can operate on existing roads



Family of Linear Motor Applications

New
Rolling
Stock



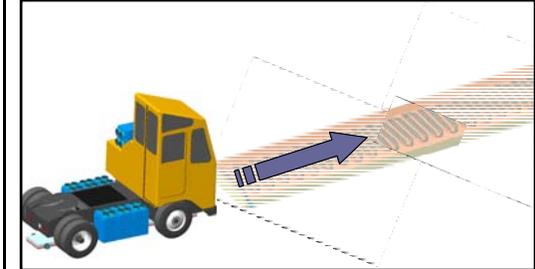
ECCO™ Maglev

- Long-distance routes
- Regional solution



LIM-Rail™ (Train Retrofit)

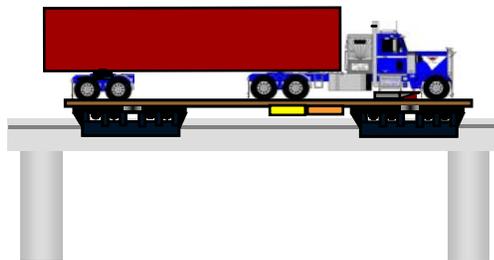
- Rail yards
- Shuttle Trains
- Alameda Corridor



MagneTruck™

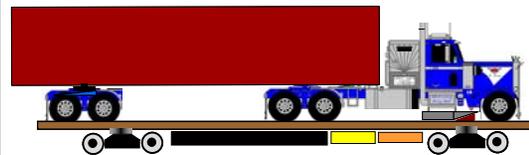
- Terminal operations
- Freeway truck lanes

Existing
Rolling
Stock



ECCO-Truck™ Maglev

- Medium-distance routes
- Eliminates extra "lifts"



LIM-Rail™ (Truck Carrier)

- Short to medium routes
- Roll-on/Roll-off



MagiCarpet™

- Weigh stations
- Border crossings

Maglev Guideway

Conventional Rail

Conventional Roadway

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ECCO™: Maglev for Freight Movement



First's First Cargo Maglev Move – June 8, 2006

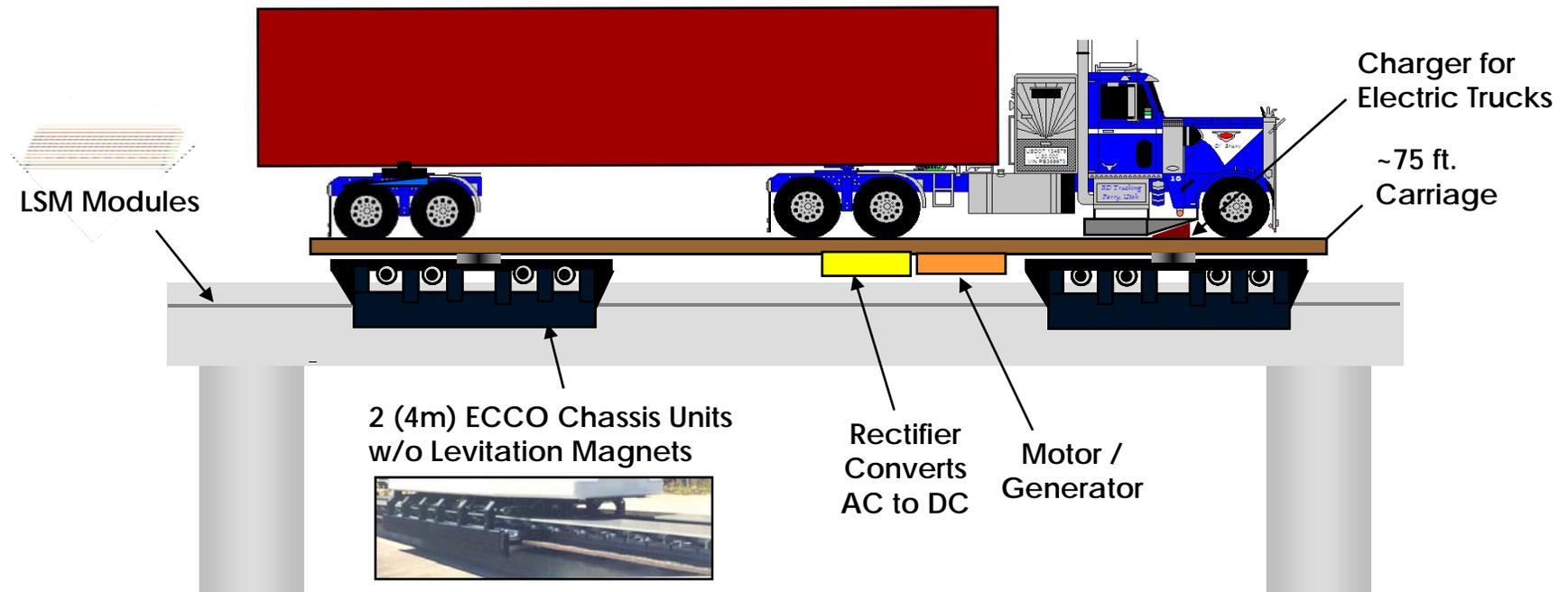
LSM Coils Being Assembled on Guideway Weldment



New Optimized Maglev Chassis on Track



ECCO™-Truck Maglev

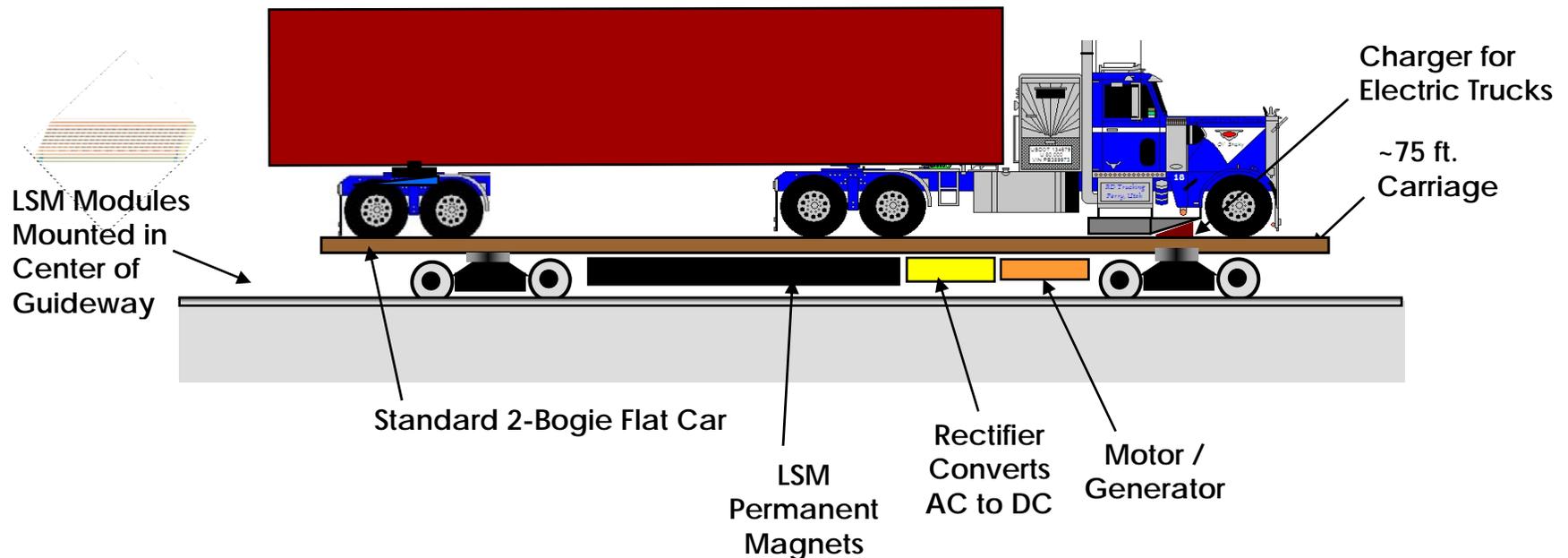


- Eliminates need for container lifts – trucks roll on and off system
- Uses 2 ECCO chassis units – can operate without levitation for on-port operations
- Uses a two-bogie system for tight turn radius
- Supports both diesel and alternative fuel trucks – including electric
- Charges electric trucks with on-board charger driven by the LSM

CONCEPTS FOR PORT-RELATED TRANSPORTATION

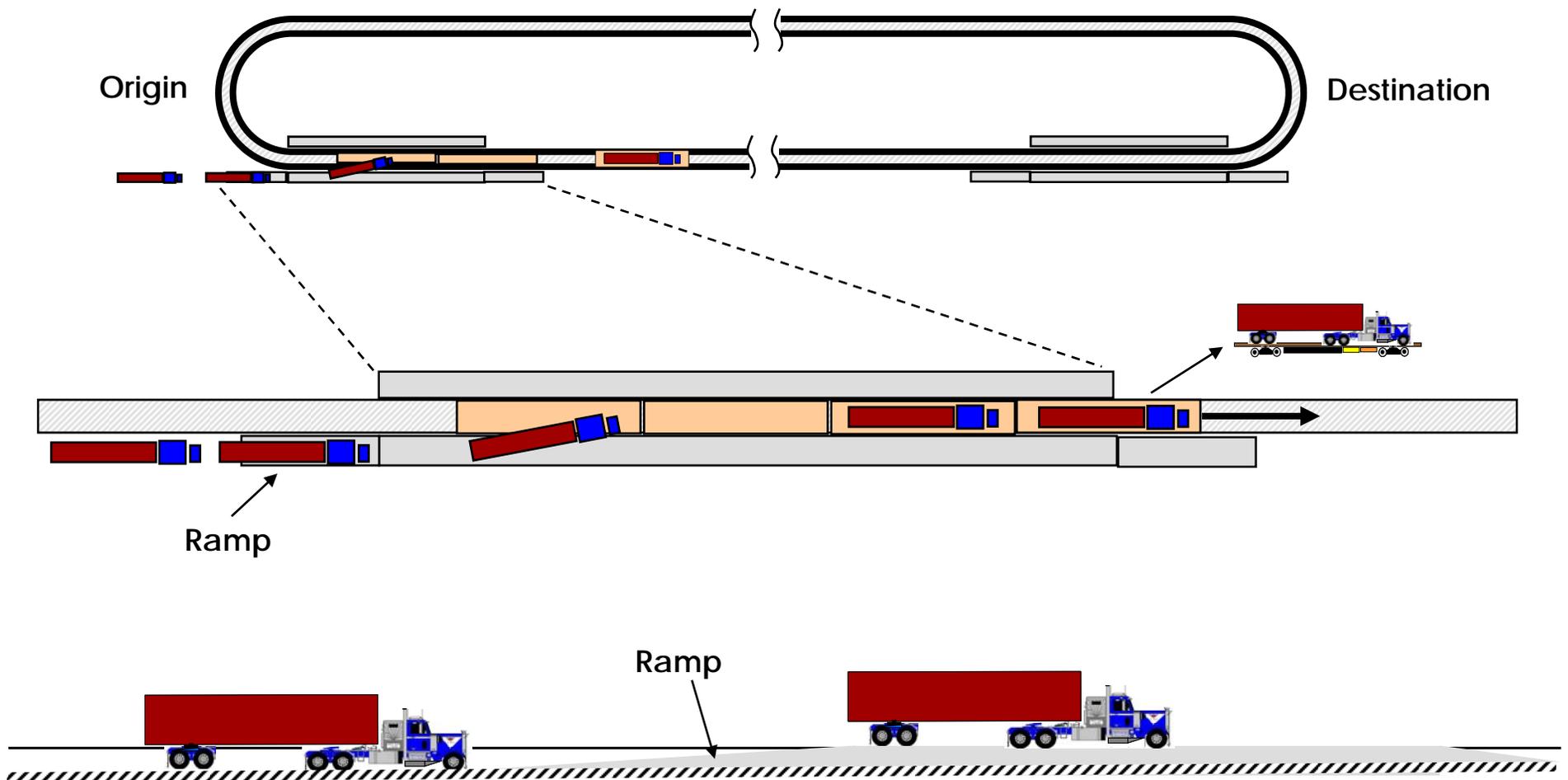
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LIM-Rail™ - Truck Carrier Option



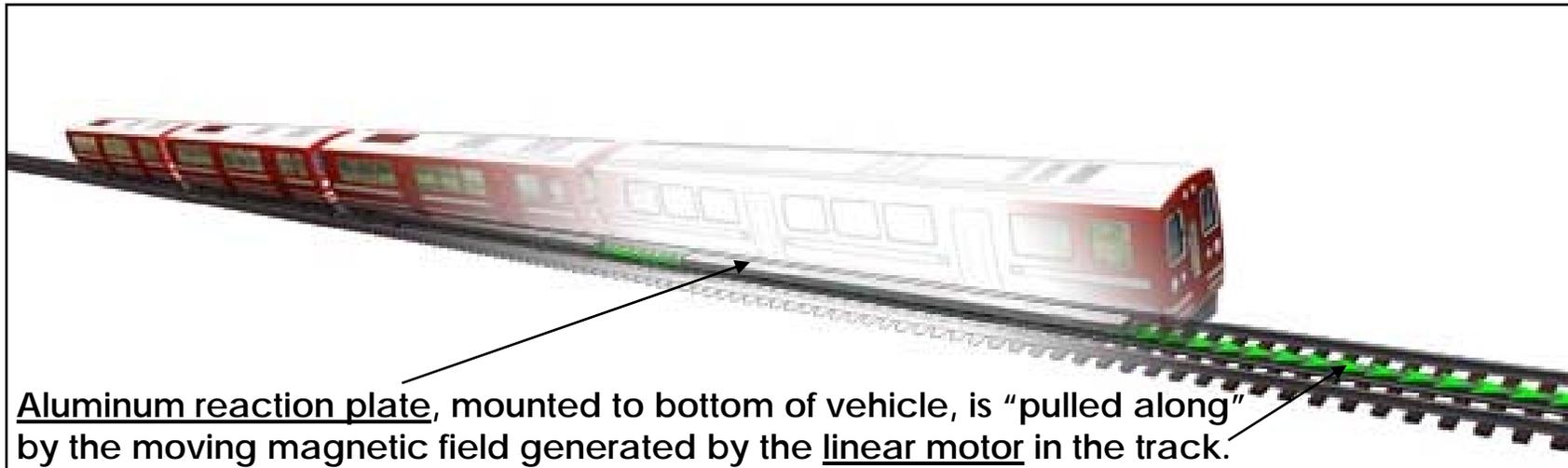
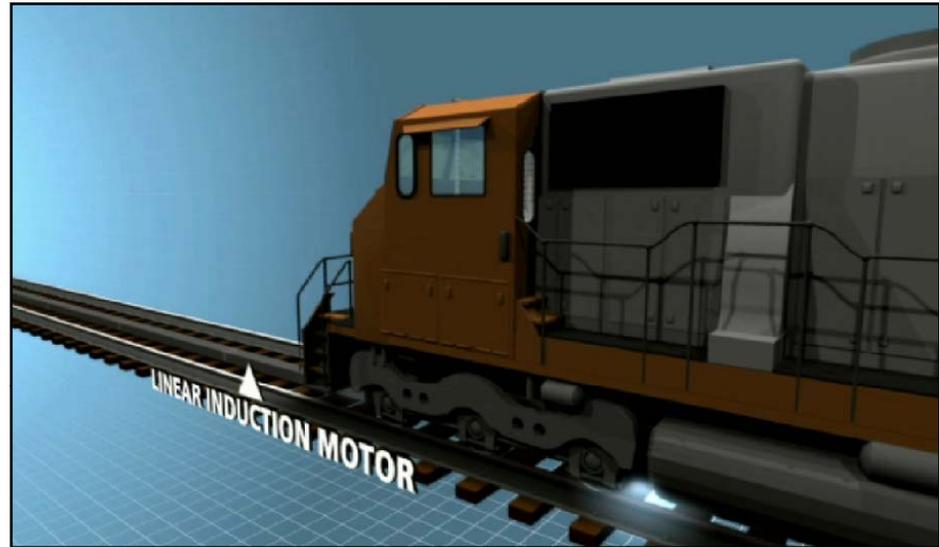
- Runs on standard rails – elevated or at grade
- Uses standard 2-bogie flat car – allowing for tight turn radius
- Trucks can roll on and off – no container lifts!
- Supports both diesel and alternative fuel trucks – including electric
- Charges electric trucks with on-board charger driven by the LSM

"Circulator" System Configuration



LIM-Rail™ - Train Retrofit Options

- Freight trains
 - Rail yards
 - Ports
 - Alameda Corridor
- Commuter rail
 - Replace diesel engines
 - Replace overhead electric “catenary” lines

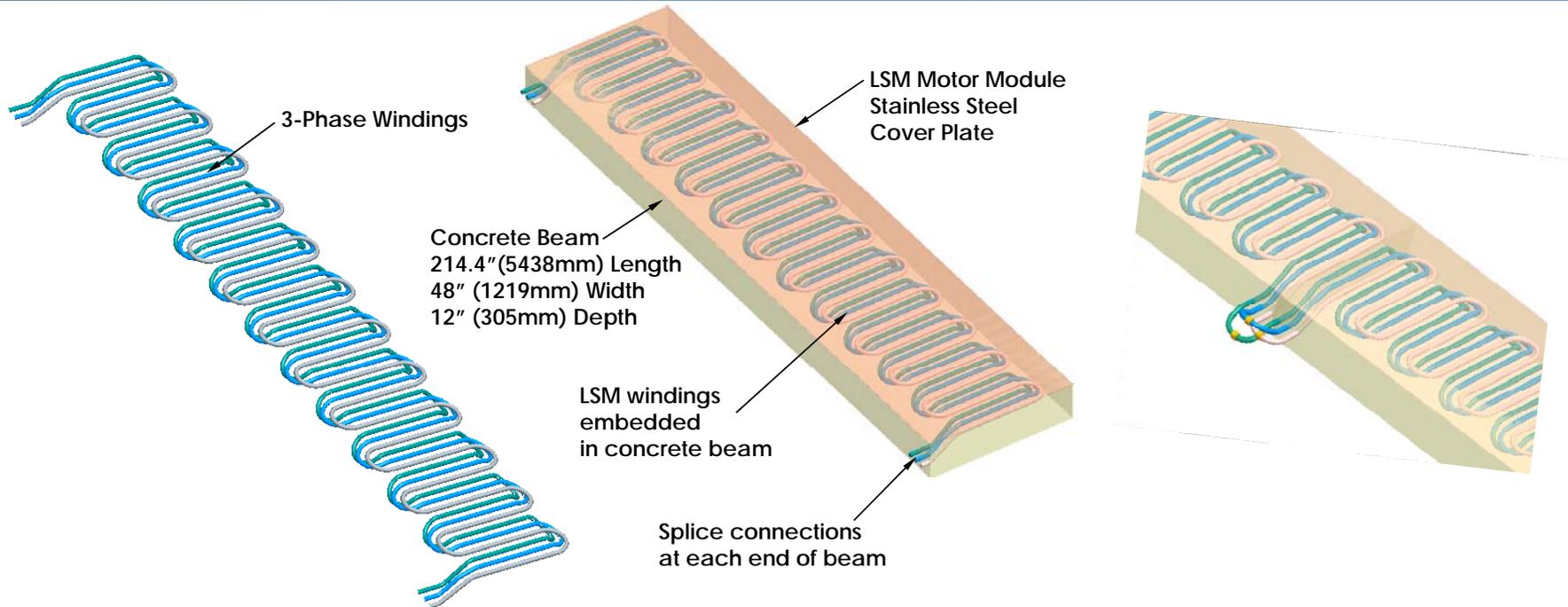


Aluminum reaction plate, mounted to bottom of vehicle, is “pulled along” by the moving magnetic field generated by the linear motor in the track.

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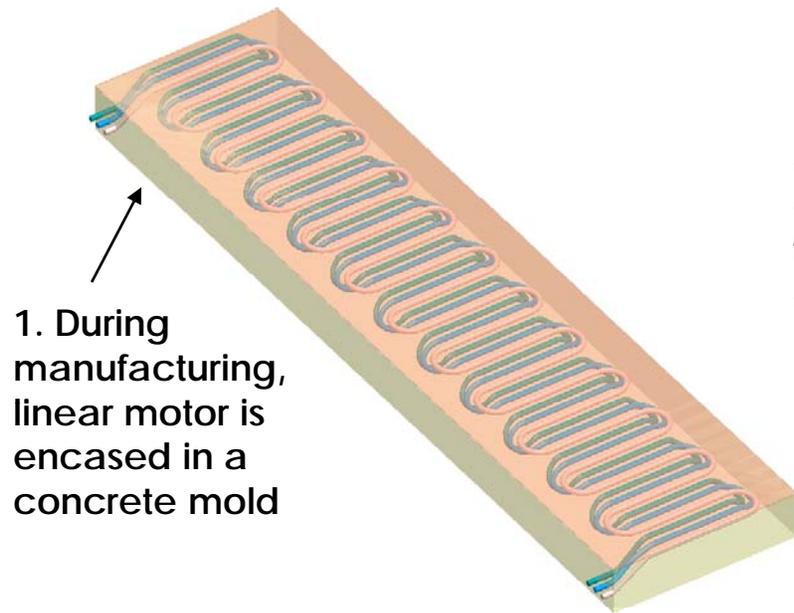
LSM Motor Modules for Road Applications*



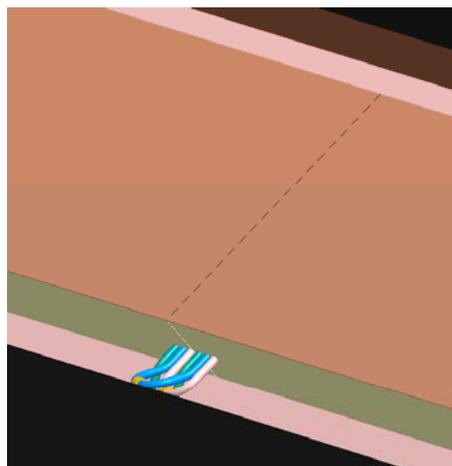
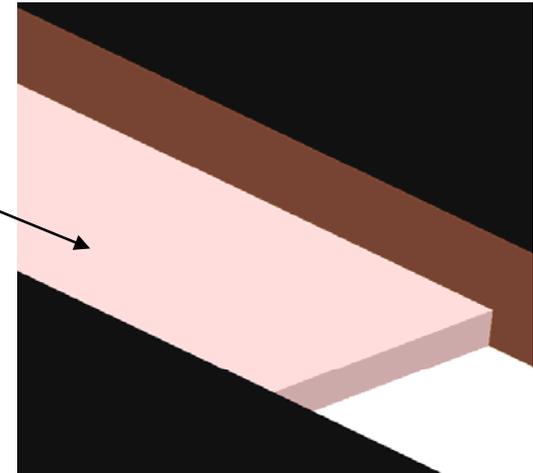
Wind LSM Cables → Encase in Concrete/Composite → Join Modules

- Simple modular design – minimum impact during construction
- Efficient electric linear motor – minimizes operating costs
- No moving parts – minimizes maintenance costs
- Provides continuous all-electric operation – no plug in required
- Automated operation – high throughput capabilities

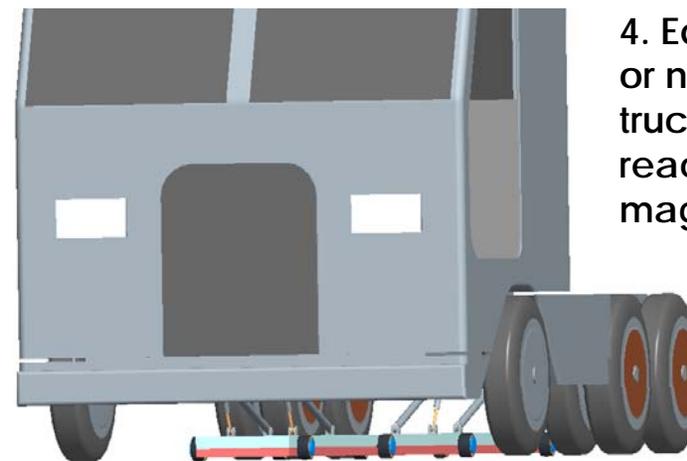
LSM Module Road Installation Process



2. In road to be electrified, excavate a trench (~18" deep x 71" wide)



3. Install linear motor block segments into roadway and connect electrical windings



4. Equip existing or new electric trucks with reaction plates or magnets

MagiCarpet™ Truck-Mover Concept

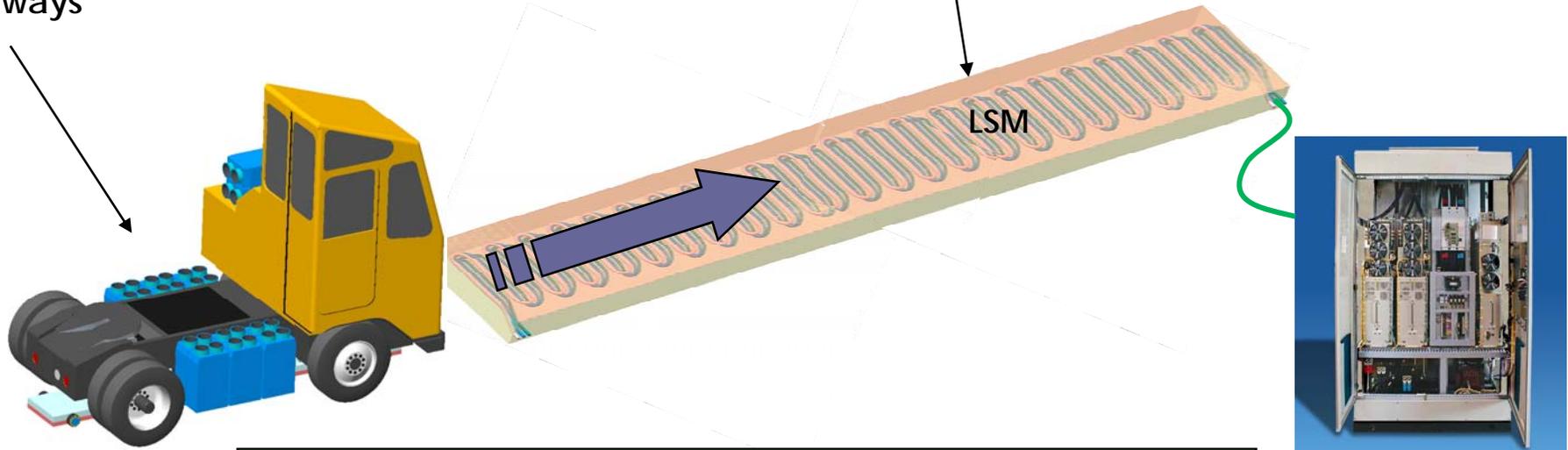


- Accommodates existing trucks
 - Trucks drive onto rolling platform
 - Engine is turned off
 - Permanent magnets in platform react against linear motor in road to pull truck
- Applications
 - Short low speed routes
 - Examples: border crossings, weigh stations, possibly port terminal applications?

MagneTruck™ Operating Scenario

Electric vehicle uses onboard batteries while operating on conventional roadways

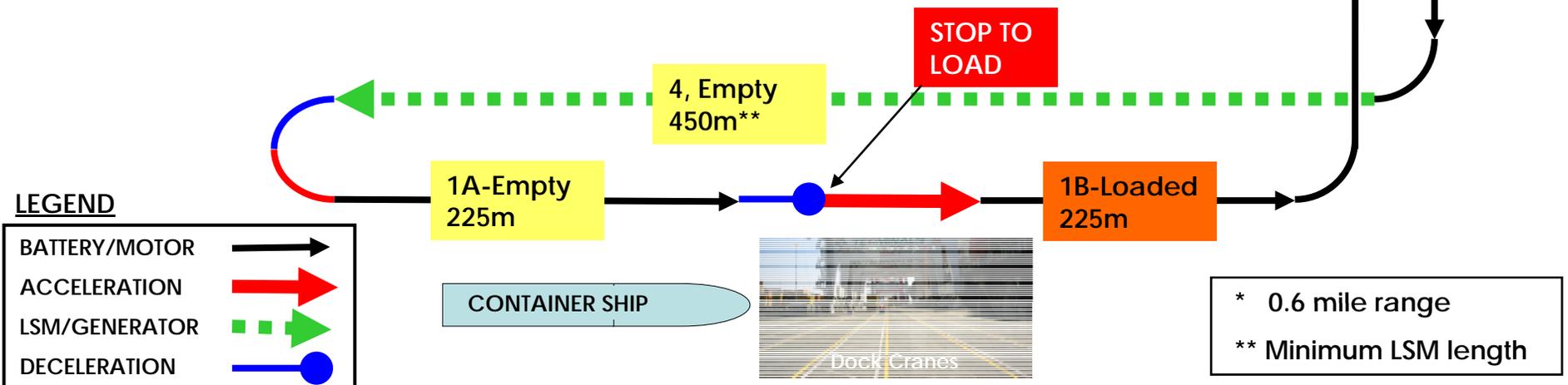
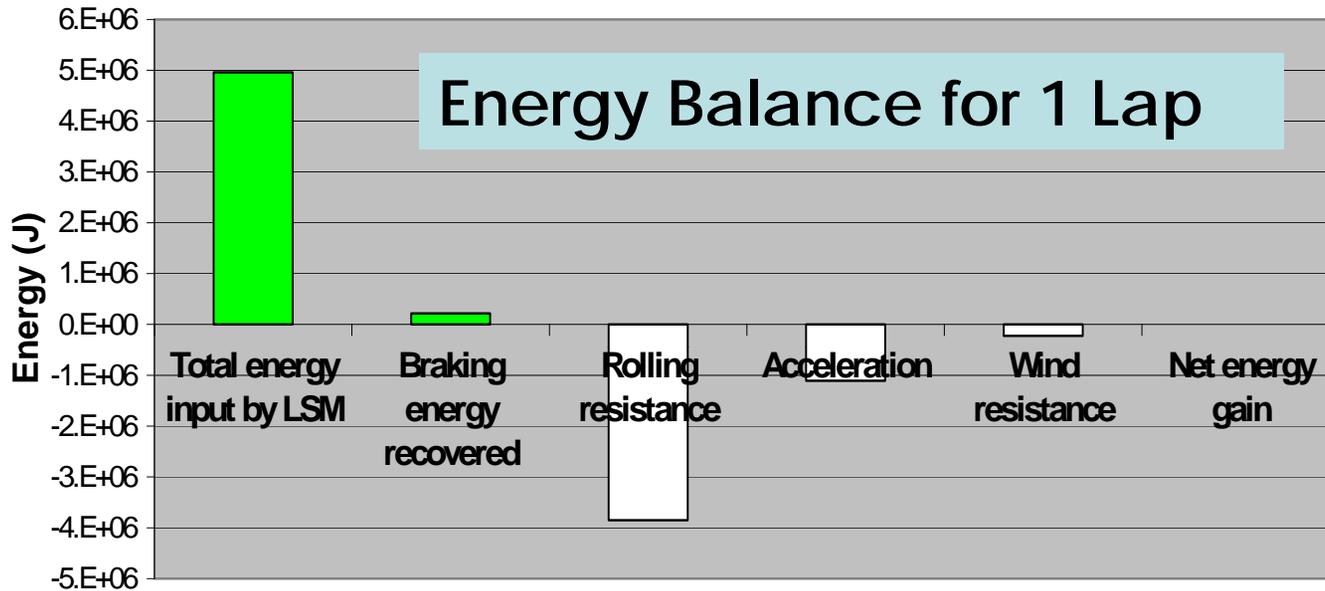
While operating on linear motor-retrofitted road (or elevated guideway) segment, power is supplied by road/guideway and batteries are simultaneously recharged



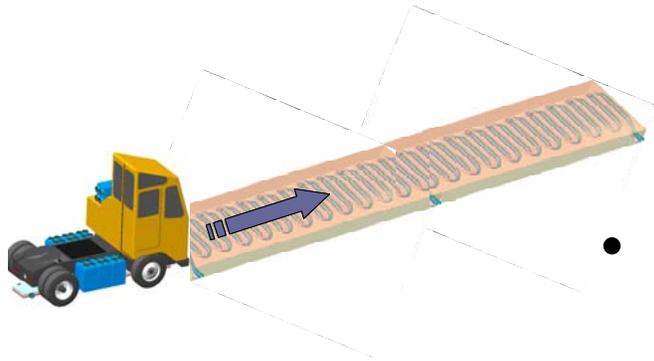
Benefits

- Trucks operate in zero-emission mode 100% of time
- Eliminates need for heavy, expensive battery packs
- Vehicles are recharged "on the go" – do not need to be removed from service to recharge batteries

Typical Terminal Operating Scenario/ Energy Balance



MagneTruck™ Freeway Example: I-710



- **Getting onto I-710**

- Driver maneuvers truck onto dedicated truck lane with linear motor in ground
- Engine is turned off
- Road provides power – driver just steers
- Batteries are recharged

- **Getting off I-710**

- Onboard electric drive motor activated
- Vehicle steers onto offramp
- Battery power used to get truck to its destination and then back to I-710



BUSINESS CONSIDERATIONS

GA Business Approach to Port Opportunity

- Private Financing

- Meet port desire for private investment in system
- Assemble strong financial team (ITSC, Macquarie, AECOM)

- Technical Approach

- Must be driven by business considerations
- Minimize up-front investment, technical risk
- Capture enough business to yield an attractive return
- Phase in more advanced capabilities as justified economically

- Logical Evolution

- Near Term – Systems like MagneTruck™ that can use existing infrastructure
- Longer Term – Systems like ECCO maglev with added benefits

Linear Motors: Already Proven in Transportation



Urban Light Rail Systems

- “Short-stator” linear motors installed on vehicles
- React against metal plate in track
- In passenger transport operations since 1987
- Examples: JFK AirTrain (New York), Detroit People-Mover



Maglev Systems

- Can use “short-stator” linear motors on vehicles or “long-stator” motors in guideway
- Transrapid system in passenger transport operations since 2005
- Other systems in development in U.S., Japan, Korea

Electric Truck Capital Cost Comparison

	Battery-Electric Truck	Magne-Truck™	Assumptions
Battery-electric operating range	50 miles	5 miles	All destinations are within 2.5 miles of linear motor roadway
Battery pack size	150 kWhr	15 kWhr	Truck consumes 3 kWhr of energy per mile
Battery pack cost	\$150,000	\$15,000	Battery pack costs \$1,000 per kWhr of usable energy capacity
Magnet array and pickup system cost	\$0	\$35,000	\$27,500 for magnets + \$7,500 for supporting equipment
Total truck cost	\$250,000	\$150,000	Balance of truck costs \$100,000 (\$50K glider + \$50K drive system)

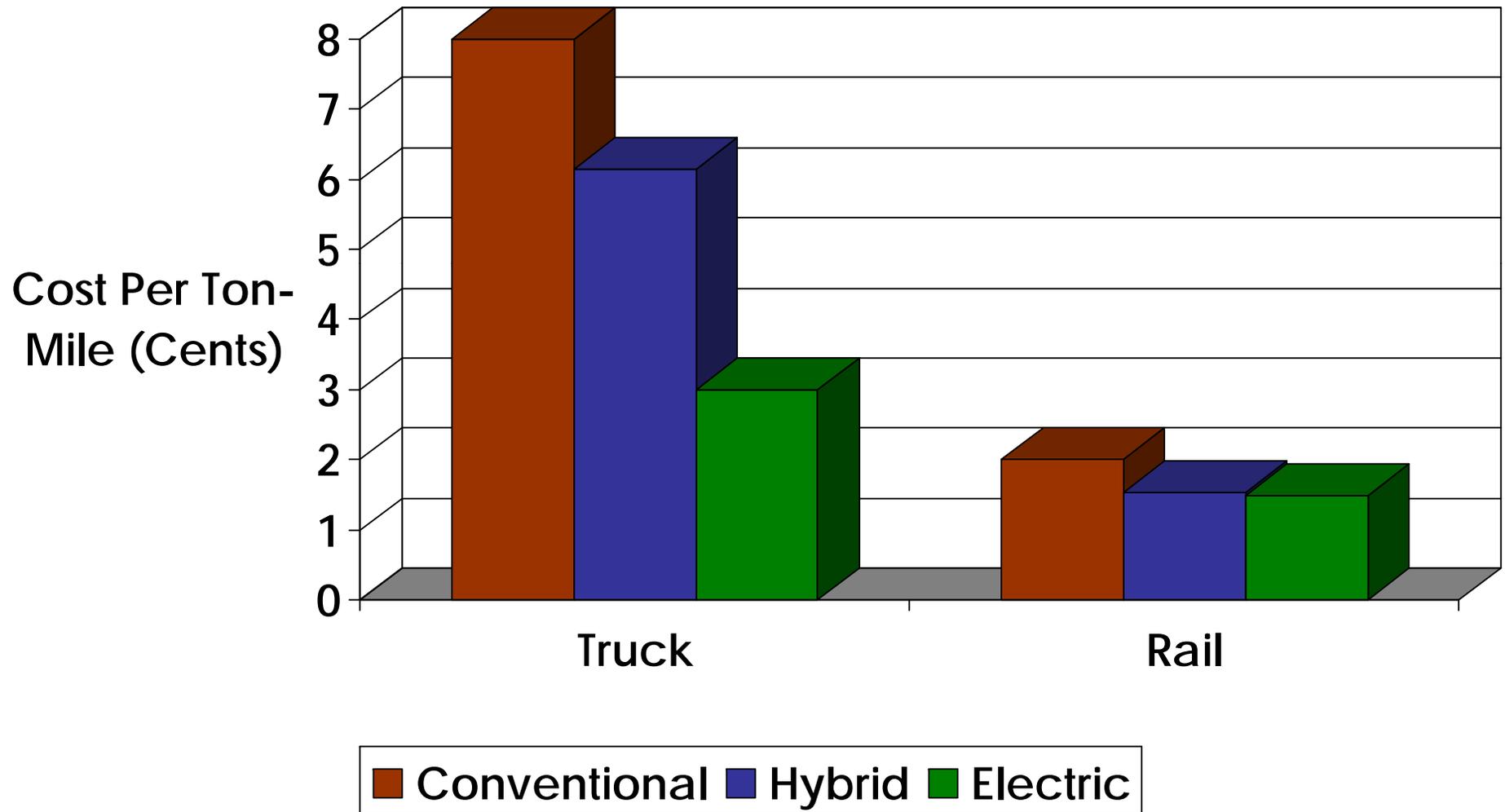
ROM planning estimates – example only

Life-Cycle Economics Comparison

	Battery-Electric Truck	Magne-Truck™	Assumptions
10-year mileage	500,000 miles	625,000 miles	Battery Truck: 4 RT/day x 250 days/year MagneTruck™: 5 RT/day x 250 days/year
Capital cost	\$250,000	\$150,000	From previous page
Battery replacement costs	\$150,000	\$15,000	One battery pack replacement during 10-year operating life
Maintenance costs	\$75,000	\$45,000	3% of capital cost per year
Energy costs	\$225,000	\$281,250	45 cents/mile based on 15 cents/kWhr
TOTAL COSTS	\$700,000	\$491,250	
Total Revenue	\$2,000,000	\$2,500,000	\$200 per round trip
NET REVENUE	\$1,300,000	\$2,008,750	Over 10 years, revenues minus costs

ROM planning estimates – example only

Transportation Electrification: Cost Impact (Cargo Transport, Based on \$8/gallon for Diesel Fuel)



Public-Private Partnership Concept

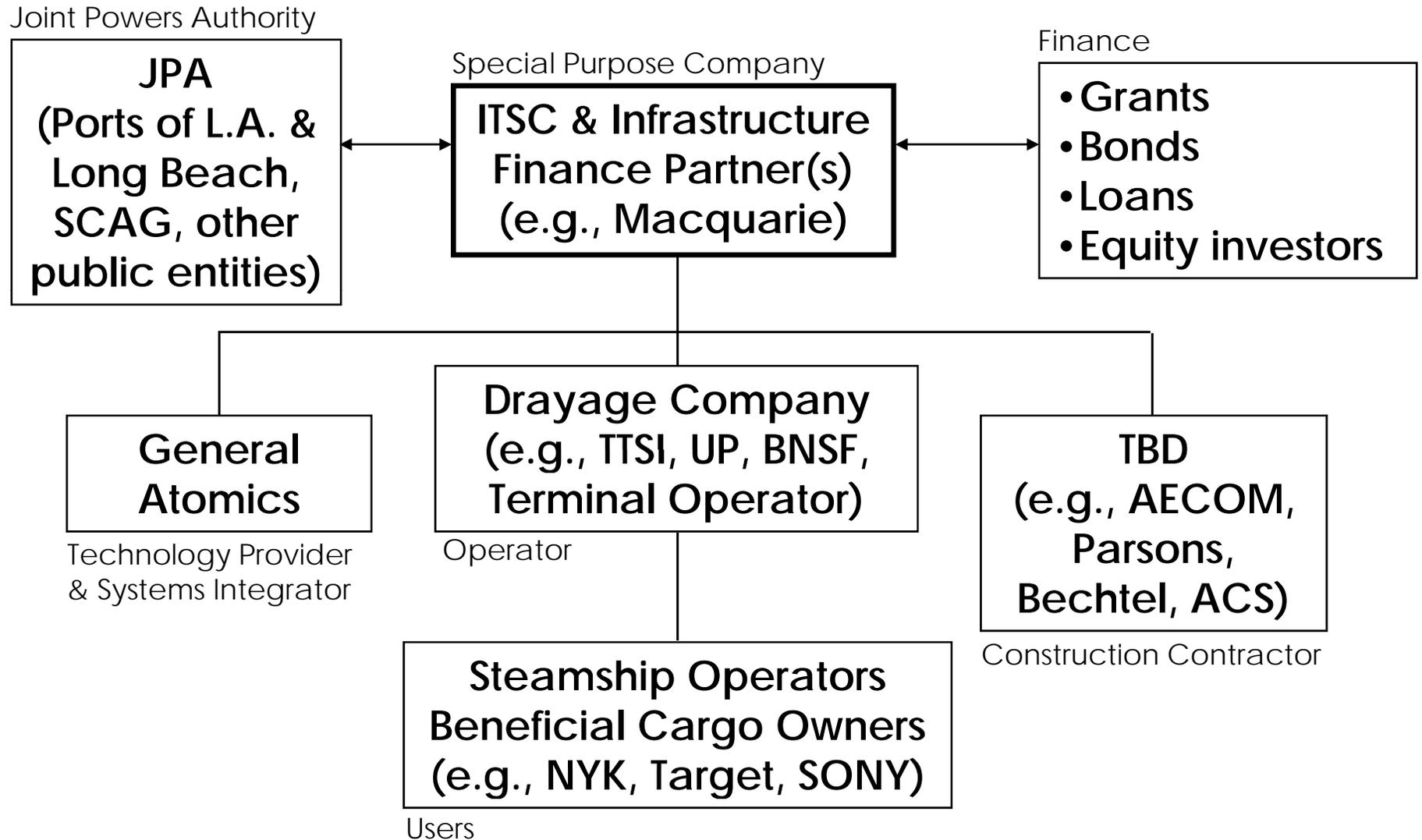
Public Sector Role

- Provide seed funding to mitigate risks
 - Environmental
 - Right-of-Way
 - Economic/Legal
- Grant maglev operating “concession”
- Establish Joint Powers Authority (JPA) to achieve above

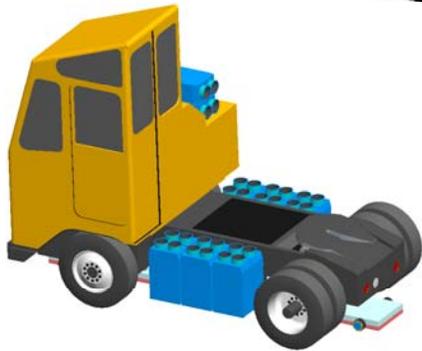
Private Sector Role

- Build and operate maglev system
- Arrange for most of maglev construction financing
 - Debt
 - Equity
- Bill users (passengers, shippers) for maglev use
 - Repay debt
 - Earn return on equity investment

Electric Cargo Mover Business Model



Conclusions



- Maglev and linear motor technologies have advanced considerably over the past decade
- Many innovative options exist for meeting port-related transportation needs
- We seek a business partnership with the ports and other stakeholders to determine the most cost-effective, profitable way to evolve linear motor-based systems